

Student's ID: _____

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University of Waterloo
Department of Electrical and Computer Engineering

**ECE 413 – DIGITAL SIGNAL PROCESSING
MIDTERM EXAM, SPRING 2007**

June 13, 2007, 5:30-7:00 PM

Instructor: Dr. Oleg Michailovich

Student's name: _____

Student's ID #: _____

INSTRUCTIONS:

- This exam has **6** pages.
- **No books and lecture notes are allowed on the exam.** Please, turn off your cell phones, PDAs, etc., and place your bags, backpacks, books, and notes under the table or at the front of the room.
- Please, place your **WATCARD** on the table, and fill out the exam attendance sheet when provided by the proctor after the exam starts.
- Answer all questions in the space provided on the exam paper. Use the back of pages if it is necessary.
- Question marks are listed by the question.
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- Be neat. Poor presentation will be penalized.
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Problem №1 (25%)

By direct evaluation of the convolution sum, determine the output of a linear time-invariant system whose impulse response is given by $h[n] = a^{-n}u[-n]$, $0 < a < 1$, where $u[n]$ is the unit step sequence given by:

$$u[n] = \begin{cases} 1, & \text{for } n \geq 0, \\ 0, & \text{for } n < 0, \end{cases}$$

when the input $x[n]$ is equal to the unit step $u[n]$ defined above. **Hint:** The following formulas may be useful (for $|a| < 1$):

$$\sum_{k=-n}^{\infty} a^k = \frac{a^{-n}}{1-a} \quad \text{and} \quad \sum_{k=0}^{\infty} a^k = \frac{1}{1-a}.$$

your answer is here ↘

Problem №2 (20%)

An LTI system has impulse response $h[n] = 5(1/2)^n u[n]$ where $u[n]$ is the unit step sequence defined in Problem 1. Use the (discrete-time) Fourier transform to find the output of this system when the input is $x[n] = (1/3)^n u[n]$. **Hints:**

- A. The Fourier transform of $x[n] = a^n u[n]$ (with $|a| < 1$) is equal to $X^f(\theta) = (1 - a e^{-j\theta})^{-1}$.
- B. Try to use a factorization of the form:

$$\frac{b_1}{1 + a_1 e^{-j\theta}} \cdot \frac{b_2}{1 - a_2 e^{-j\theta}} = \frac{c_1}{1 + a_1 e^{-j\theta}} + \frac{c_2}{1 - a_2 e^{-j\theta}}.$$

your answer is here ↘

Problem №3 (20%)

The continuous-time signal $x(t) = \sin(20\pi t) + \cos(40\pi t)$ is sampled with a sampling period T to obtain the discrete-time signal

$$x[n] = \sin\left(\frac{\pi n}{5}\right) + \cos\left(\frac{2\pi n}{5}\right).$$

- A. Determine a choice of T consistent with this information.
- B. Is your choice of T in Part A unique? If so, explain why. If not, specify another choice of T consistent with the information given.

your answer is here ↘

Problem №4 (25%)

Consider the complex sequence:

$$x[n] = \begin{cases} e^{j\theta_0 n}, & 0 \leq n \leq N-1, \\ 0, & \text{otherwise.} \end{cases}$$

- A. Find the Fourier transform $X^f(\theta)$ of $x[n]$.
- B. Find the N -point DFT $X^d[k]$ of the finite-length sequence $x[n]$.
- C. Find the DFT of $x[n]$ for the case $\theta_0 = 2\pi k_0/N$, where k_0 is an integer.

your answer is here ↘

Problem №5 (10%)

Let X_1 and X_2 be two $N \times N$ *circulant* matrices corresponding to finite-dimensional sequences $x_1[n]$ and $x_2[n]$ of length N , respectively. Find a general expression for the (k, n) -th element of matrix Y that is equal to the product of X_1 and X_2 , viz. $Y = X_1 X_2$. **Hint:** How is Y related to signal $y[n] = \{x_1 \otimes x_2\}[n]$?

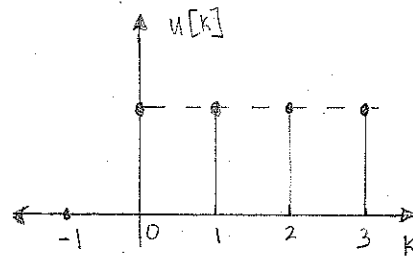
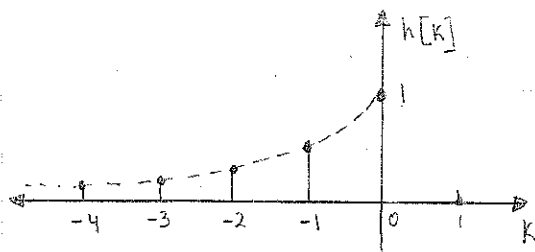
your answer is here ↘

Problem 1

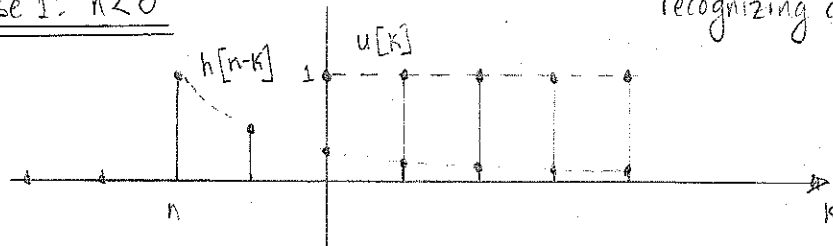
$$h[n] = a^{-n} u[-n], \quad 0 < a < 1$$

$$u[n] = \begin{cases} 1, & \text{for } n \geq 0 \\ 0, & \text{for } n < 0 \end{cases}$$

$$y[n] = \sum_{k=-\infty}^{\infty} h[n-k] u[k] \quad \leftarrow \text{writing convolution formula down (10 marks)}$$



Case 1: $n < 0$



recognizing cases (6 marks)

From the graph above: $y[n] = \sum_{k=0}^{\infty} h[n-k] u[k]$ (since $u[k] = 0, k < 0$)

choosing correct strategy (9 marks) \rightarrow getting right answer $= \sum_{k=0}^{\infty} \underbrace{a^{-(n-k)} u[-(n-k)]}_{h[n-k]} u[k]$

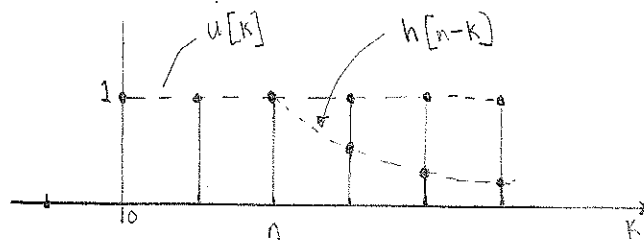
Note: $u[k-n] \cdot u[k] = u[k]$
(since $n < 0$)

$$= \sum_{k=0}^{\infty} a^{k-n} u[k-n] u[k]$$

$$= \sum_{k=0}^{\infty} a^{k-n} u[k]$$

$$= \sum_{k=-n}^{\infty} a^k = \frac{a^{-n}}{1-a} \quad (\text{from hint})$$

Case 2: $n > 0$



From the graph above: $y[n] = \sum_{k=0}^{\infty} h[n-k] u[k]$ (since $u[k] = 0, k < 0$)

$$= \sum_{k=0}^{\infty} a^{-(n-k)} \underbrace{u[-(n-k)]}_{h[n-k]} u[k]$$

$$= \sum_{k=0}^{\infty} a^{k-n} u[k-n] u[k]$$

$$= \sum_{k=0}^{\infty} a^{k-n} u[k-n]$$

$$= \sum_{k=n}^{\infty} a^{k-n}$$

$$= \sum_{k=0}^{\infty} a^k$$

$$= \frac{1}{1-a} \quad (\text{from hint})$$



Note:

$$u[k-n] \cdot u[k] = u[k-n]$$

(since $n > 0$)

Problem 2

$$h[n] = 5 \left(-\frac{1}{2}\right)^n u[n] \iff H^f(\theta) = \frac{5}{1 + \left(\frac{1}{2}\right)e^{-j\theta}} \quad (\text{from Hint A}) \quad (1)$$

$$x[n] = \left(\frac{1}{3}\right)^n u[n] \iff X^f(\theta) = \frac{1}{1 - \left(\frac{1}{3}\right)e^{-j\theta}} \quad (\text{from Hint A}) \quad (2)$$

$$\text{Now, } y[n] = h[n] * x[n] \quad (3)$$

$$\Rightarrow Y^f(\theta) = H^f(\theta) X^f(\theta) \quad (4)$$

10 marks

Substituting (1) and (2) into (4):

$$Y^f(\theta) = \left(\frac{5}{1 + \left(\frac{1}{2}\right)e^{-j\theta}} \right) \left(\frac{1}{1 - \left(\frac{1}{3}\right)e^{-j\theta}} \right) \quad (5)$$

4 marks for correct substitution

$$\boxed{11 \text{ mark}} \quad = \frac{C_1}{1 + \left(\frac{1}{2}\right)e^{-j\theta}} + \frac{C_2}{1 - \left(\frac{1}{3}\right)e^{-j\theta}} \quad (\text{from hint}) \quad (6)$$

We need to find C_1 and C_2 . From (5) and (6) it follows that for all θ :

$$C_1 \left[1 - \left(\frac{1}{2}\right)e^{-j\theta} \right] + C_2 \left[1 + \left(\frac{1}{2}\right)e^{-j\theta} \right] = 5 \quad (7)$$

substituting $\theta = 0$ into (7):

$$C_1 \left(1 - \frac{1}{2} \right) + C_2 \left(1 + \frac{1}{2} \right) = 5$$

$$\Rightarrow \frac{2C_1}{3} + \frac{3C_2}{2} = 5 \quad (8)$$

Similarly, for $\theta = \pi$:

$$C_1 \left(1 + \frac{1}{3}\right) + C_2 \left(1 - \frac{1}{2}\right) = 5$$

$$\frac{4C_1}{3} + \frac{C_2}{2} = 5 \quad (9)$$

Solving (8) and (9) for C_1 & C_2 :

$$\frac{4C_1}{3} + 3C_2 = 10 \quad (\text{Eq. 8}) \times 2$$

$$- \frac{4C_1}{3} + \frac{C_2}{2} = 5$$

$$\frac{5C_2}{2} = 5$$

$$C_2 = 2$$

(10)

Substitute (10) into (9) or (8):

$$\frac{4C_1}{3} + \frac{2}{2} = 5$$

$$C_1 = 3$$

3 marks for correct
 C_1 & C_2

(11)

Therefore from (10), (11), (6) and Hint A,

2 marks

$$y[n] = 3 \left(-\frac{1}{2}\right)^n u[n] + 2 \left(\frac{1}{3}\right)^n u[n]$$



Problem 3


$$x(t) = \sin(20\pi t) + \cos(40\pi t)$$

$$x[n] = x(nT_s) = \sin\left(\frac{\pi n}{5}\right) + \cos\left(\frac{2\pi n}{5}\right)$$

Part A

Suppose $T_s = \frac{1}{100}$. Then clearly:

$$\begin{aligned} x(nT_s) &= \sin(20\pi nT_s) + \cos(40\pi nT_s) \\ &= \sin\left(\frac{\pi n}{5}\right) + \cos\left(\frac{2\pi n}{5}\right) \end{aligned}$$

So an obvious choice of T_s is $T_s = \frac{1}{100}$ 

10 marks

Part B

First we determine the period of $x(t)$. Note that the $\sin(20\pi t)$ term has period $T_1 = 0.1$ ($\frac{2\pi}{T_1} = 20\pi$). The

$\cos(40\pi t)$ term has period $T_2 = 0.05$ ($\frac{2\pi}{T_2} = 40\pi$). Therefore

the period of $x(t)$ is the least common multiple of T_1 & T_2 ; the period must be $T = 0.1$.

So we have: $x(t) = x(t + kT) \quad \forall k, T = 0.1$

Therefore $x(nT_s) = x(nT_s + kT) \quad \forall k$

Now suppose we sample at $T_s' = T_s + mT$, where m is some integer, and $T = 0.1$ (the period of $x(t)$)

$$\text{Then } x(nT'_s) = x(n(T_s + mT))$$

$$= x(nT_s + nmT)$$

$$= x(nT_s)$$

Therefore T_s is clearly not unique. Any sampling period

$T_s = \frac{1}{100} + k(0.1)$ is consistent with the information given

5 marks for saying " T_s is not unique"

5 marks for providing an alternative T_s

If your answer was incorrect, you received up to 5 marks for mentioning the word "periodic" in your explanation.

Problem 4

$$x[n] = \begin{cases} e^{j\theta_0 n}, & 0 \leq n \leq N-1 \\ 0, & \text{otherwise.} \end{cases}$$

$$X^f(\theta) = \sum_{n=0}^{N-1} x[n] e^{-j\theta n}$$

$$= \sum_{n=0}^{N-1} e^{-j(\theta-\theta_0)n}$$

7.5 marks for getting here

2.5 marks
for geometric
series formula
(anywhere)

$$= \frac{1 - e^{-j(\theta-\theta_0)N}}{1 - e^{-j(\theta-\theta_0)}}$$

(since we have the sum of a
geometric series)

(*)

$$= \frac{\exp\left(-j\frac{(\theta-\theta_0)N}{2}\right) \left(\exp\left(j\frac{(\theta-\theta_0)N}{2}\right) - \exp\left(-j\frac{(\theta-\theta_0)N}{2}\right) \right)}{\exp\left(-j\frac{(\theta-\theta_0)}{2}\right) \left(\exp\left(j\frac{(\theta-\theta_0)}{2}\right) - \exp\left(-j\frac{(\theta-\theta_0)}{2}\right) \right)}$$

$$= \frac{\exp\left(-j\frac{(\theta-\theta_0)(N-1)}{2}\right) \sin\left(\frac{(\theta-\theta_0)N}{2}\right)}{\sin\left(\frac{\theta-\theta_0}{2}\right)}$$

Part B

$$X^d[k] = X^f\left(\frac{2\pi k}{N}\right) = \frac{\exp\left(-j0.5\left(\frac{2\pi k}{N} - \theta_0\right)(N-1)\right) \sin\left(0.5\left(\frac{2\pi k}{N} - \theta_0\right)N\right)}{\sin\left(0.5\left(\frac{2\pi k}{N} - \theta_0\right)\right)}$$

4 marks for correct formula of DFT

1 mark

for answer in simplified form (as in (*))

or

5 marks

→ for recognizing $X^d[k] = X^f\left(\frac{2\pi k}{N}\right)$

Part C

Suppose $\theta_0 = \frac{2\pi k_0}{N}$, where k_0 is an integer.

Then,

$$X^d[k] = \exp\left(-j0.5\left(\frac{2\pi k}{N} - \frac{2\pi k_0}{N}\right)(N-1)\right) \frac{\sin\left(0.5\left(\frac{2\pi k}{N} - \frac{2\pi k_0}{N}\right)N\right)}{\sin\left(0.5\left(\frac{2\pi k}{N} - \frac{2\pi k_0}{N}\right)\right)}$$

We have two cases, $k \neq k_0$ and $k = k_0$.

Case 1: $k \neq k_0$

The sin term in the numerator is zero. The denominator is non-zero.

$$\therefore X^d[k] = 0$$

Case 2: $k = k_0$

Notice the ratio of sin terms can be expressed as follows:

$$\begin{aligned} \frac{\sin\left(0.5\left(\frac{2\pi k}{N} - \frac{2\pi k_0}{N}\right)N\right)}{\sin\left(0.5\left(\frac{2\pi k}{N} - \frac{2\pi k_0}{N}\right)\right)} &= \frac{\sin\left(\pi(k-k_0)\right)}{\sin\left(\pi\left(\frac{k-k_0}{N}\right)\right)} \cdot \frac{\pi\left(\frac{k-k_0}{N}\right)}{\pi(k-k_0)} \cdot N \\ &= \frac{\text{sinc}\left(k-k_0\right)}{\text{sinc}\left(\frac{k-k_0}{N}\right)} \cdot N \end{aligned}$$

Therefore $X^d[k_0] = \frac{\text{sinc}(0)}{\text{sinc}(0)} \cdot N$
 $= N$

The final solution is :

$$X^d[k] = \begin{cases} 0, & k \neq k_0 \\ N, & k = k_0 \end{cases}$$

Alternate (easier) solution to part c

$$X^d[k] = \sum_{n=0}^{N-1} e^{j2\pi n} W_N^{-nk} \leftarrow \boxed{6 \text{ marks}} \text{ for stating formula.}$$

$$= \sum_{n=0}^{N-1} W_N^{k_0 n} W_N^{-nk}$$

$$= \sum_{n=0}^{N-1} W_N^{-n(k-k_0)} \leftarrow \boxed{7.5 \text{ marks}} \text{ for getting to this form}$$

$$= N \delta[(k-k_0) \bmod N]$$

$$\boxed{2.5 \text{ marks}} \text{ for this answer.}$$

Problem 5

We know $y[n] = \{x_1 \otimes x_2\}[n]$

Also, $Y = X_1 X_2$, where X_1 and X_2 are circulant matrices corresponding to $x_1[n]$ and $x_2[n]$.

We now prove that Y must be the circulant matrix corresponding to $y[n]$.

Suppose we have a column vector Z corresponding to a sequence $z[n]$.

Let Y' be the circulant matrix corresponding to $y[n]$.

$$\begin{aligned} \text{Let } W[n] &= \{y \otimes z\}[n] \\ &= \{x_1 \otimes x_2 \otimes z\}[n] \end{aligned}$$

Therefore $W = X_1 X_2 Z$ and $W = Y' Z$, where W is the column vector corresponding to $w[n]$.

$$\text{So } Y' = X_1 X_2 = Y$$

Therefore Y must be the circulant matrix corresponding to $y[n]$.

$$\text{Hence } Y_{k,n} = y[(k-n) \bmod N] \quad \blacksquare$$

10 marks for correct final answer

or 9 marks for stating Y is the circulant corresponding to $y[n]$

or 8 marks for recognizing relationship between convolution and multiplication by circulant

or 7 marks for knowing general form of circulant matrix + painful calculations

or 6 marks for painful calculations

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University of Waterloo
Department of Electrical and Computer Engineering

**ECE 413 – DIGITAL SIGNAL PROCESSING
FINAL EXAM, SPRING 2007**

August 4, 2007, 12:30-3:00 PM

Instructor: Dr. Oleg Michailovich

Student's name: _____

Student's ID #: _____

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Problem №1 (18%)

The linear filter $h[n]$ with transfer function

$$H^f(\theta) = \begin{cases} -j, & 0 < \theta < \pi, \\ j, & -\pi < \theta < 0, \end{cases}$$

is used to generate signal $y[n]$, such that $\Re\{y[n]\} = x[n]$ and $\Im\{y[n]\} = \{x * h\}[n]$ (with \Re and \Im denoting the real and imaginary parts, respectively, viz. $y[n] = \Re\{y[n]\} + j\Im\{y[n]\}$) for some input signal $x[n]$. Given that the Fourier transform $X^f(\theta)$ of $x[n]$ is defined as

$$\Re\{X^f(\theta)\} = \begin{cases} 0, & -\pi \leq \theta < -\theta_0, \\ \frac{\theta}{\theta_0} + 1, & -\theta_0 \leq \theta < 0, \\ 1 - \frac{\theta}{\theta_0}, & 0 \leq \theta < \theta_0, \\ 0, & \theta_0 \leq \theta \leq \pi, \end{cases} \quad \text{and} \quad \Im\{X^f(\theta)\} = 0, \quad -\pi \leq \theta \leq \pi,$$

for some $0 < \theta_0 < \pi$, determine and sketch $Y^f(\theta)$.

your answer is here ↘

Problem №2 (23%)

When the input to an LTI system is

$$x[n] = \left(\frac{1}{2}\right)^n u[n] + 2^n u[-n-1],$$

the output is

$$y[n] = 6 \left(\frac{1}{2}\right)^n u[n] - 6 \left(\frac{3}{4}\right)^n u[n],$$

when $u[n]$ is the unit-step function.

- A. Find the transfer function $H(z)$ of the system. Plot the poles and zeros of $H(z)$, and indicate the region of convergence.
- B. Find the impulse response $h[n]$ of the system.
- C. Write the difference equation that characterizes the system.
- D. If the system stable? Is it causal?

Problem №3 (18%)

Consider a stable discrete-time signal $x[n]$ whose discrete-time Fourier transform $X^f(\theta)$ satisfies the equation

$$X^f(\theta) = X^f(\theta - \pi),$$

and has even symmetry, i.e., $x[n] = x[-n]$.

- A. Show that $X^f(\theta)$ is periodic with a period π .
- B. Find the value of $x[3]$. (Hint: Find values of all odd-indexed samples.)
- C. Let $y[n]$ be a decimated version of $x[n]$, viz. $y[n] = x[2n]$. Can you reconstruct $x[n]$ from $y[n]$ for all n ? If yes, how? If no, justify your answer.

your answer is here ↘

Problem №4 (23%)

The transfer function of a discrete-time system is

$$H(z) = \frac{2}{1 - e^{-0.2}z^{-1}} - \frac{1}{1 - e^{-0.4}z^{-1}}. \quad (1)$$

Assume that $H(z)$ was obtained by the bilinear transform method with $T = 2$. Find the (continuous-time) transfer function $H^S(s)$ that could be the basis for the design. Is your answer unique? If not, find another $H^S(s)$.

your answer is here ↘

Problem №5 (18%)

Consider the following ideal frequency response for a multi-band filter:

$$H_d(\theta) = \begin{cases} e^{-j\theta N/2}, & 0 \leq |\theta| \leq 0.3\pi, \\ 0, & 0.3\pi < |\theta| < 0.6\pi, \\ 0.5e^{-j\theta N/2}, & 0.6\pi \leq |\theta| \leq \pi. \end{cases}$$

The impulse response $h_d[n]$ is multiplied by a Hamming window with $N = 51$, resulting in a linear-phase FIR filter with impulse response $h[n]$.

- A. What is the delay of the filter $h[n]$?
- B. Determine the ideal impulse response $h_d[n]$.

your answer is here ↘

Problem #1

Note that $X(e^{j\omega})$ is real, and $Y(e^{j\omega})$ is given by:

$$Y(e^{j\omega}) = \begin{cases} -jX(e^{j\omega}) & , 0 < \omega < \pi \\ +jX(e^{j\omega}) & , -\pi < \omega < 0. \end{cases}$$

$w[n] = x[n] + jy[n]$, therefore:

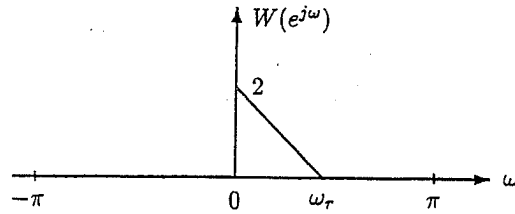
$$W(e^{j\omega}) = X(e^{j\omega}) + jY(e^{j\omega}).$$

Using the above, we get:

$$jY(e^{j\omega}) = \begin{cases} X(e^{j\omega}) & , 0 < \omega < \pi \\ -X(e^{j\omega}) & , -\pi < \omega < 0. \end{cases}$$

We thus conclude:

$$W(e^{j\omega}) = \begin{cases} 2X(e^{j\omega}) & , 0 < \omega < \pi \\ 0 & , -\pi < \omega < 0. \end{cases}$$



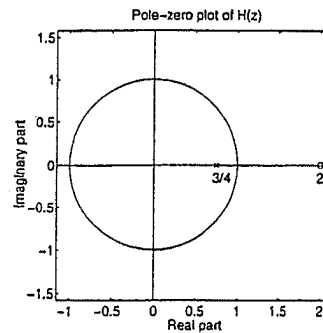
Problem #2

(a)

$$X(z) = \frac{1}{1 - \frac{1}{2}z^{-1}} - \frac{1}{1 - 2z^{-1}}, \quad \frac{1}{2} < |z| < 2$$

$$Y(z) = \frac{6}{1 - \frac{1}{2}z^{-1}} - \frac{6}{1 - \frac{3}{4}z^{-1}}, \quad |z| > \frac{3}{4}$$

$$\begin{aligned} H(z) &= \frac{Y(z)}{X(z)} = \frac{\frac{-\frac{3}{2}z^{-1}}{(1 - \frac{1}{2}z^{-1})(1 - \frac{3}{4}z^{-1})}}{\frac{-\frac{3}{2}z^{-1}}{(1 - \frac{1}{2}z^{-1})(1 - 2z^{-1})}} \\ &= \frac{1 - 2z^{-1}}{1 - \frac{3}{4}z^{-1}}, \quad |z| > \frac{3}{4} \end{aligned}$$



(b)

$$h[n] = \left(\frac{3}{4}\right)^n u[n] - 2 \left(\frac{3}{4}\right)^{n-1} u[n-1]$$

(c)

$$y[n] - \frac{3}{4}y[n-1] = x[n] - 2x[n-1]$$

(d) The system is stable because the ROC includes the unit circle. It is also causal since $h[n] = 0$ for $n < 0$.

Problem #3

- (a) Since $X(e^{j\omega}) = X(e^{j(\omega-\pi)})$, $X(e^{j\omega})$ is periodic with period π .
 (b) Using the inverse DTFT,

$$\begin{aligned} x[n] &= \frac{1}{2\pi} \int_{\langle 2\pi \rangle} X(e^{j\omega}) e^{j\omega n} d\omega \\ &= \frac{1}{2\pi} \int_{\langle 2\pi \rangle} X(e^{j(\omega-\pi)}) e^{j\omega n} d\omega \\ &= \frac{1}{2\pi} \int_{\langle 2\pi \rangle} X(e^{j\omega}) e^{j(\omega+\pi)n} d\omega \\ &= \frac{1}{2\pi} e^{j\pi n} \int_{\langle 2\pi \rangle} X(e^{j\omega}) e^{j\omega n} d\omega \\ &= (-1)^n x[n]. \end{aligned}$$

All odd samples of $x[n] = 0$, because $x[n] = -x[n]$. Hence $x[3] = 0$.

- (c) Yes, $y[n]$ contains all even samples of $x[n]$, and all odd samples of $x[n]$ are 0.

$$x[n] = \begin{cases} y[n/2], & n \text{ even} \\ 0, & \text{otherwise} \end{cases}$$

Problem #4

Using the inverse relationship for the bilinear transform,

$$z = \frac{1 + (T_d/2)s}{1 - (T_d/2)s}$$

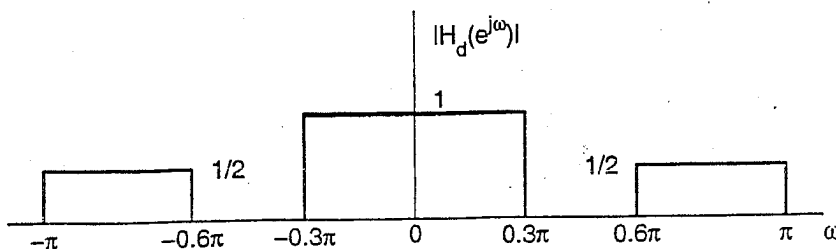
we get

$$\begin{aligned} H_c(s) &= \frac{2}{1 - e^{-0.2} \left(\frac{1-s}{1+s} \right)} - \frac{1}{1 - e^{-0.4} \left(\frac{1-s}{1+s} \right)} \\ &= \frac{2(s+1)}{s(1+e^{-0.2}) + (1-e^{-0.2})} - \frac{(s+1)}{s(1+e^{-0.4}) + (1-e^{-0.4})} \\ &= \left(\frac{2}{1+e^{-0.2}} \right) \left(\frac{s+1}{s + \frac{1-e^{-0.2}}{1+e^{-0.2}}} \right) - \left(\frac{1}{1+e^{-0.4}} \right) \left(\frac{s+1}{s + \frac{1-e^{-0.4}}{1+e^{-0.4}}} \right) \end{aligned}$$

Since the bilinear transform does not introduce any ambiguity, the representation is unique.

Problem #5

- (a) The delay is $\frac{M}{2} = 24$.
 (b)



This can be viewed as the sum of two lowpass filters, one of which has been shifted in frequency (modulation in time-domain) to $\omega = \pi$. The linear phase factor adds a delay.

$$h_d[n] = \frac{\sin(0.3\pi(n-24))}{\pi(n-24)} + \frac{1}{2}(-1)^{(n-24)} \frac{\sin(0.4\pi(n-24))}{\pi(n-24)}$$