# Representations of $\mathfrak{sl}(3, \mathbf{C})$

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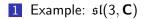
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(slides are a work in progress)

# Overview



# The attack plan

To carry out a similar analysis of the Lie algebra  $\mathfrak{g} := \mathfrak{sl}(3, \mathbb{C})$ , we will use essentially the same strategy as we did for  $\mathfrak{sl}(2, \mathbb{C})$ , although some slight generalizations must be made.

Once this is done, however, no further concepts need be introduced to classify all finite-dimensional representations of the remaining semisimple Lie algebras.

Recall that our previous analysis of  $\mathfrak{sl}(2, \mathbf{C})$  was based on a decomposition into eigenspaces for the action of the matrix

$${\cal H}=egin{pmatrix} 1&0\0&-1\end{pmatrix}.$$

A similar thing will work here, although we need to instead look at the action of the subspace  $\mathfrak{h} \subset \mathfrak{g}$  of *all* (traceless) diagonal matrices.

# Eigenspaces of $\mathfrak{h}$

Let V be a finite-dimensional representation of  $\mathfrak{g} = \mathfrak{sl}(3, \mathbf{C})$ .

Observation

Commuting diagonalizable matrices are simultaneously diagonalizable.

Therefore, as before, V admits a decomposition  $V = \bigoplus V_{\alpha}$ , where each  $v \in V_{\alpha}$  is an eigenvector for *every*  $H \in \mathfrak{h}$ .

## Definition

 $v \in V$  is called an **eigenvector for**  $\mathfrak{h}$  if it is an eigenvector for every  $H \in \mathfrak{h}$ .

For such a vector v, we can write (note that as usual, the representation is implicit on the LHS):

$$H(v) = \alpha(H) \cdot v \tag{(*)}$$

with  $\alpha$  depending linearly on  $H \in \mathfrak{h}$ , that is,  $\alpha \in \mathfrak{h}^*$  (here,  $\mathfrak{h}^*$  is the dual space of  $\mathfrak{h}$ ; it consists of all linear maps  $\mathfrak{h} \to \mathbf{C}$ ).

This motivates us to generalize the concept of eigenvalue as follows.

## Definition

 $\alpha \in \mathfrak{h}^*$  is called an **eigenvalue for**  $\mathfrak{h}$  if there exists a nonzero  $v \in V$  such that (\*) holds. The **eigenspace associated to**  $\alpha$  is defined to be the subspace consisting of all  $v \in V$  satisfying (\*).

We can recast our previous statement in this new language as follows: any finite-dimensional representation V of  $\mathfrak{g}$  decomposes as  $V = \bigoplus V_{\alpha}$ where  $V_{\alpha}$  is an eigenspace for  $\mathfrak{h}$  and  $\alpha$  runs over a finite subset of  $\mathfrak{h}^*$ .

Recall the commutation relations we saw for  $\mathfrak{sl}(2, \mathbf{C})$ ,

$$\underbrace{[H,X]}_{\mathrm{ad}(H)(X)} = 2X, \qquad [H,Y] = -2Y.$$

We should interpret these as saying that X and Y are *eigenvectors for* the adjoint action of H on  $\mathfrak{sl}(2, \mathbb{C})$ . It seems, then, that to continue, we should look for eigenvectors for the adjoint action of  $\mathfrak{h}$  on  $\mathfrak{sl}(3, \mathbb{C})$ !

# Eigenvectors for the adjoint action of $\mathfrak{h}$ on $\mathfrak{g}$

By taking  $V = \mathfrak{sl}(3, \mathbb{C})$  to be the adjoint representation of  $\mathfrak{g}$ , we can apply our previous remark to obtain a decomposition

$$\mathfrak{g} = \mathfrak{h} \oplus \big( \bigoplus_{\alpha} \mathfrak{g}_{\alpha} \big) \tag{D1}$$

(here we have just pulled  $\mathfrak{h} = \mathfrak{g}_0$  out front) where  $\alpha$  runs over a finite subset of  $\mathfrak{h}^*$  and we have for any  $H \in \mathfrak{h}$  and  $Y \in \mathfrak{g}_{\alpha}$  that

$$[H, Y] = \mathsf{ad}(H)(Y) = \alpha(H) \cdot Y.$$

What kind of matrices  $M = (m_{ij})$  could possibly be eigenvectors for  $\mathfrak{h}$ ? Well, if  $D = \text{diag}(a_1, a_2, a_3)$  then  $(DM)_{ij} = a_i \cdot m_{ij}$  and  $(MD)_{ij} = a_j \cdot m_{ij}$ , so that

$$[D, M]_{ij} = (DM)_{ij} - (MD)_{ij} = (a_i - a_j)m_{ij}.$$
 (\*\*)

#### Observation

[D, M] is a multiple of M for all  $D \in \mathfrak{h}$  if and only if  $m_{ij} = 0$  for all but one choice of (i, j).

Hence, if we let as usual  $E_{ij}$  denote the matrix with 1 in entry (i, j) and 0 everywhere else, the  $E_{ij}$  exactly generate the eigenspaces for the adjoint action of  $\mathfrak{h}$  on  $\mathfrak{g}$ .

Note that since

$$\mathfrak{h} = \left\{ \begin{pmatrix} a_1 & 0 & 0 \\ 0 & a_2 & 0 \\ 0 & 0 & a_3 \end{pmatrix} : a_1 + a_2 + a_3 = 0 \right\}$$

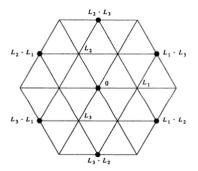
we can realize its dual space  $\mathfrak{h}^*$  as the quotient by the annihilator:

$$\mathfrak{h}^* = \mathbf{C}\{L_1, L_2, L_3\}/(L_1 + L_2 + L_3)$$

where  $L_i$  sends diag $(a_1, a_2, a_3) \mapsto a_i$ . This is a general fact from linear algebra; if  $W \subseteq V$  is a subspace, then  $W^*$  is isomorphic to the *quotient* of  $V^*$  by the subspace Ann $(W) \subseteq V^*$  consisting of all linear functionals which vanish on all of W. Indeed, restricting functionals to W yields a (clearly surjective) map  $V^* \rightarrow W^*$  whose kernel is precisely Ann(W).

# The root lattice

In view of calculation (\*\*), there are six functionals  $\alpha \in \mathfrak{h}^*$  appearing in the direct sum decomposition of  $\mathfrak{g}$ , namely  $L_i - L_j$  for  $i \neq j$ . If we draw  $L_1$ ,  $L_2$  and  $L_3$  in the two-dimensional space  $\mathfrak{h}^*$ , it is a hexagonal lattice:



We have plotted the six eigenvalues  $L_i - L_j \in \mathfrak{h}^*$  on the lattice. The matrix  $E_{ij}$  generates the eigenspace  $\mathfrak{g}_{L_i-L_j}$ . By definition,  $\operatorname{ad}(\mathfrak{h})$  maps each  $\mathfrak{g}_{\alpha}$  into itself. Our next task is to determine how the rest of  $\mathfrak{g}$  acts.

# A concrete way to write down roots

Since we can explicitly exhibit a basis for the space  $\mathfrak{h}$ , namely

$$\mathcal{H}_1 = egin{pmatrix} 1 & 0 & 0 \ 0 & -1 & 0 \ 0 & 0 & 0 \end{pmatrix}, \qquad \mathcal{H}_2 = egin{pmatrix} 0 & 0 & 0 \ 0 & 1 & 0 \ 0 & 0 & -1 \end{pmatrix}$$

it may be more concrete to write the roots  $\alpha \in \mathfrak{h}^*$  simply as ordered pairs of complex numbers, in terms of their values on this basis. That is,  $\alpha$  may be represented by the ordered pair  $(\alpha(H_1), \alpha(H_2))$ . If we do this, we see that the roots are:

$$(2, -1)$$
  
 $(-1, 2)$   
 $(1, 1)$   
 $(-2, 1)$   
 $(1, -2)$   
 $(-1, -1).$ 

# Determining the adjoint action of $\mathfrak{g}_{\alpha}$ on $\mathfrak{g}$

To do this, let's take some  $X \in \mathfrak{g}_{\alpha}$ , some  $Y \in \mathfrak{g}_{\beta}$ , and figure out where ad(X)(Y) lives. Let  $H \in \mathfrak{h}$  be arbitrary, and calculate:

$$[H, [X, Y]] = [[H, X], Y] + [X, [H, Y]]$$
(by Jacobi identity)  
$$= [\alpha(H) \cdot X, Y] + [X, \beta(H) \cdot Y]$$
$$= (\alpha + \beta)(H) \cdot [X, Y].$$

#### Conclusion

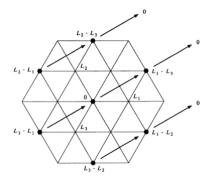
[X, Y] = ad(X)(Y) is again an eigenvector for  $\mathfrak{h}$  with eigenvalue  $\alpha + \beta$ . Hence,

$$\operatorname{\mathsf{ad}}(\mathfrak{g}_lpha):\mathfrak{g}_eta o\mathfrak{g}_{lpha+eta}.$$

Notice that this is the same calculation we did for  $\mathfrak{sl}(2, \mathbb{C})$  last week. Repeating it almost verbatim, we can show that given *any* representation V, the action of  $\mathfrak{g}_{\alpha}$  carries  $V_{\beta}$  into  $V_{\alpha+\beta}$ .

In the adjoint representation,  $\mathfrak{g}_{\alpha}$  therefore acts "by translation" in the sense that it maps the eigenspace corresponding to a dot on the lattice to the eigenspace corresponding to the translation of that dot by  $\alpha$ .

For example, here is how  $\mathfrak{g}_{L_1-L_3}$  acts:



Similarly to last week (by contriving some subspace W and showing it's invariant), we make the following observation.

## Observation

The eigenvalues  $\alpha$  occurring in any any irreducible representation V of  $\mathfrak{sl}(3, \mathbb{C})$  differ from one another by integral linear combinations of the  $L_i - L_j \in \mathfrak{h}^*$ .

The lattice in  $\mathfrak{h}^*$  generated by the  $L_i - L_j$  will be called  $\Lambda_R$  (the **root** lattice).

## Definition

The eigenvalue  $\alpha \in \mathfrak{h}^*$  of the action of  $\mathfrak{h}$  on a representation V of  $\mathfrak{g}$  is called a **weight** of the representation, the corresponding eigenvectors are called **weight vectors**, and the eigenspaces  $V_{\alpha}$  are called **weight spaces**. The nonzero weights of the adjoint representation are called **roots** of  $\mathfrak{g}$ , and the  $\mathfrak{g}_{\alpha} \subset \mathfrak{g}$  are called **root spaces**.

# Finding the extremal eigenspace

Recall that in our analysis of  $\mathfrak{sl}(2, \mathbb{C})$ , our next step was to consider a "highest weight vector", that is, a vector in some "extremal" eigenspace  $V_{\alpha}$ .

In the current situation this translates to "choosing a direction" and then looking for the furthest  $\alpha$  appearing in that direction. To be precise, we select a linear functional  $\ell : \Lambda_R \to \mathbf{R}$ , extend it by linearity to a linear functional  $\ell : \mathfrak{h}^* \to \mathbf{C}$ , and then go to the eigenspace  $V_{\alpha}$  for which  $\ell(\alpha)$ (or say, its real part) is largest. We'll see the choice of  $\ell$  doesn't matter.

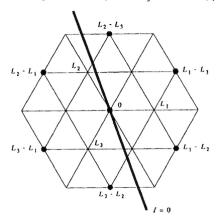
### Observation

If we choose  $\ell$  so that its kernel contains a lattice point, it is easy to see that we may run into non-uniqueness of this  $\alpha$ . Thus we should choose  $\ell$  to be irrational with respect to the lattice.

Using this strategy we may find a vector  $v \in V_{\alpha}$  that is an eigenvector for  $\mathfrak{h}$  and simultaneously killed by all of the "positive" root spaces  $\mathfrak{g}_{\beta}$ (here by "positive" we mean  $\ell(\beta) > 0$ ). Representations of  $\mathfrak{sl}(3, \mathbf{C})$ 

Example: sl(3, C)

Let's just say we want the kernel of  $\ell$  to look like this (so that the positive root spaces are generated by the  $E_{ij}$  with i < j):



Then we should choose  $\ell$  to be given by

$$\ell(a_1L_1 + a_2L_2 + a_3L_3) = aa_1 + ba_2 + ca_3$$

with a > b > c. For  $\ell$  to be well-defined, we also need a + b + c = 0.

Thus for i < j,  $E_{ij}$  generate the positive root spaces, and  $E_{ji}$  generate the negative root spaces. Let

$$H_{ij}=[E_{ij},E_{ji}]=E_{ii}-E_{jj}.$$

By our work above, we have established:

### Lemma

There is a vector  $v \in V$  such that

- v is an eigenvector for  $\mathfrak{h}$ , i.e.  $v \in V_{\alpha}$  for some  $\alpha$ , and
- v is killed by  $E_{12}$ ,  $E_{13}$  and  $E_{23}$ .

Such v is called, naturally, a highest weight vector.

# How do the negative root spaces act on v?

For  $\mathfrak{sl}(2, \mathbb{C})$  we saw that, having chosen such a highest weight vector  $v \in V_n$ , the images of v under successive applications of Y (the generator of the only "negative" root space) then generated V.

Similarly, here we have

### Claim

Let V be an irreducible representation of  $\mathfrak{sl}(3, \mathbb{C})$  and  $v \in V$  a highest weight vector. Then V is generated by the images of v under successive applications of  $E_{21}$ ,  $E_{31}$  and  $E_{32}$ .

### Proof

Let W be this subspace; we claim W is invariant. Need to show W is preserved by  $E_{12}$ ,  $E_{23}$  and  $E_{13}$  (suffices to only check the first two since  $E_{13} = [E_{12}, E_{23}]$ ). Since v is a highest weight vector, it is killed by  $E_{12}$ ,  $E_{23}$  and  $E_{13}$ , so that's fine.

# Proof (continued)

Now we check that  $E_{21}v$  stays in W when  $E_{12}$  and  $E_{23}$  act on it.

$$E_{12}(E_{21}v) = E_{21}(\underbrace{E_{12}v}_{=0}) + \underbrace{[E_{12}, E_{21}]}_{\in \mathfrak{h}}v = 0 + \alpha([E_{12}, E_{21}])v. \qquad \checkmark$$
$$E_{23}(E_{21}v) = E_{21}(\underbrace{E_{23}v}_{=0}) + \underbrace{[E_{23}, E_{21}]}_{=0}v = 0. \qquad \checkmark$$

Identical computations show that  $E_{32}v$  stays in W as well.

Now we use induction. Let  $w_n$  be any word of length  $\leq n$  in the symbols  $E_{21}$  and  $E_{32}$  and let  $W_n$  be the space spanned by  $w_n(v)$  for all such words. Note  $W = \bigcup W_n$  since  $E_{31} = [E_{32}, E_{21}]$ . We claim  $E_{12}$  and  $E_{23}$  carry  $W_n$  into  $W_{n-1}$ . Indeed, write  $w_n$  as either  $E_{21} \circ w_{n-1}$  or  $E_{32} \circ w_{n-1}$ . Then

$$E_{12}(w_n(v)) = E_{12}(E_{21}(w_{n-1}v)) = E_{21}(E_{12}w_{n-1}v) + [E_{12}, E_{21}]w_{n-1}v$$
  
=  $E_{21}(W_{n-2}) + \beta([E_{12}, E_{21}])w_{n-1}v$ 

so this lands in  $W_{n-1}$ . The other cases are identical; see Fulton & Harris.

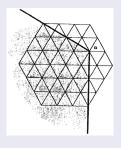
Representations of  $\mathfrak{sl}(3, \mathbf{C})$ 

Example: sl(3, C)

Some corollaries of the last claim include:

Corollary

All of the weights  $\beta \in \mathfrak{h}^*$  of V lie in a  $\frac{1}{3}$ -plane with corner  $\alpha$ :



## Corollary

dim  $V_{\alpha} = 1$ , furthermore the spaces  $V_{\alpha+n(L_2-L_1)}$  and  $V_{\alpha+n(L_3-L_2)}$  are all at most 1-dimensional; they must be spanned by  $(E_{21})^n(v)$  and  $(E_{32})^n(v)$  respectively.

In fact, the proof of the claim shows the following.

## Proposition

If V is any representation of  $\mathfrak{sl}(3, \mathbb{C})$  and  $v \in V$  is a highest weight vector, then the subrepresentation W of V generated by the images of v by successive applications of  $E_{21}$ ,  $E_{31}$ , and  $E_{32}$  is irreducible.

## Proof

Decompose  $W = W' \oplus W''$ . Projection to W' and W'' commute with the action of  $\mathfrak{h}$ , so  $W_{\alpha} = W'_{\alpha} \oplus W''_{\alpha}$ . So one of these spaces is zero, hence v belongs to W' or W'', and hence W = W' or W = W''.

As a corollary, each irrep of  $\mathfrak{sl}(3, \mathbb{C})$  has a unique highest weight vector up to scaling (thus, a unique one-dimensional subspace of HWVs). [**Note**: this seems to be clear, even without the above – how can two  $\frac{1}{3}$ -planes with different corners be the same?]

The set of HWVs of a (general) rep will be a union of linear subspaces  $\Psi_W$  corresponding to the irreducible subreps W of V, with dim  $\Psi_W$  being the multiplicity of W in the irreducible decomposition of V.

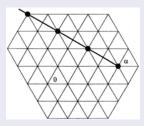
# Border vectors

## Observation

The vectors  $(E_{21})^k(v)$  span a "line" of weight spaces

$$V_{\alpha}, V_{\alpha+L_2-L_1}, V_{\alpha+2(L_2-L_1)}, \ldots$$

Furthermore, this is an uninterrupted string of nonzero eigenspaces  $V_{\alpha+k(L_2-L_1)} \cong \mathbf{C}$  until we get to the first *m* such that  $(E_{21})^m(v) = 0$ ; after that we have  $V_{\alpha+k(L_2-L_1)} = 0$  for all  $k \ge m$ :



How long is this string? The answer to this question (and the rest of this part of our analysis) will simply make use of what we already know about  $\mathfrak{sl}(2, \mathbf{C})$ .

## Observation

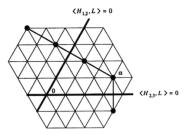
For any i < j, the elements  $E_{ij}$ ,  $E_{ji}$  and  $H_{ij}$  span a subalgebra  $\mathfrak{s}_{L_i-L_j}$  of  $\mathfrak{sl}(3, \mathbb{C})$  isomorphic to  $\mathfrak{sl}(2, \mathbb{C})$ ;  $E_{ij}$  plays the role of X,  $E_{ji}$  that of Y, and their commutator  $H_{ij}$  that of H.

In particular, take (i,j) = (1,2). We see that

$$W = \bigoplus_{k} V_{\alpha+k(L_2-L_1)}$$

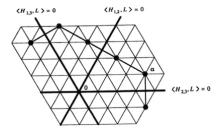
is invariant under the action of  $\mathfrak{s}_{L_1-L_2}$  and thus is a representation of  $\mathfrak{s}_{L_1-L_2} \cong \mathfrak{sl}(2, \mathbb{C})$ . Our discussion of  $\mathfrak{sl}(2, \mathbb{C})$  then implies that the eigenvalues of  $H_{12}$  on W are integral and symmetric about zero!

This means the string of dots must be preserved under reflection in the line  $\langle H_{12}, L \rangle = 0$ . Looking instead now at the subalgebra  $\mathfrak{s}_{L_2-L_3}$ , we see that the string of eigenspaces  $V_{\alpha+k(L_3-L_2)}$  is preserved under reflection in the line  $\langle H_{23}, L \rangle = 0$ :



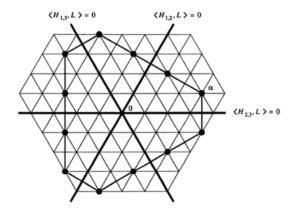
Now consider the last weight space in the first string: let  $\beta = \alpha + (m-1)(L_2 - L_1)$  where *m* is the smallest integer with  $(E_{21})^m(v) = 0$ . Let  $v' \in V_\beta$  be any nonzero vector; observe v' is killed by  $E_{21}$ ,  $E_{23}$  and  $E_{13}$ . Thus v' is a highest weight vector if we choose the functional  $\ell$  with b > a > c rather than a > b > c!

If we carry out all the analysis with respect to v' instead of v, we make a similar " $\frac{1}{3}$ -plane" observation, and also note that the strings of eigenvalues on the lines through  $\beta$  in the  $L_1 - L_2$  and  $L_3 - L_1$  directions are symmetric about the lines  $\langle H_{12}, L \rangle = 0$  and  $\langle H_{13}, L \rangle = 0$  respectively.



Example:  $\mathfrak{sl}(3, \mathbf{C})$ 

Anyway, we keep playing this same game until we conclude that the set of weights of V are bounded by a hexagon symmetric with respect to the lines  $\langle H_{ii}, L \rangle = 0$  and with one vertex at  $\alpha$ .



## Proposition

All weights of an irreducible finite-dimensional representation V must be integral linear combinations of the  $L_i$ , and be congruent modulo the lattice generated by the  $L_i - L_j$ .

Now, apply the same strategy as above to other "lines", it follows that all the points in the interior that are congruent to the others modulo the lattice  $\Lambda_R$  must also occur (although we don't know anything about their multiplicities... we will answer that question later):

