

$$= - \int_{\Omega} \left(\sum_n \frac{\varphi_n(\xi, \eta) \varphi_n(x, y)}{\lambda_n \|\varphi_n\|^2} \right) F(\xi, \eta) d\xi d\eta.$$

Therefore the Green's function representation is

$$u(x) = \int_{\Omega} G(\xi; x) F(\xi) d\xi.$$

By comparison,

$$G(\xi; x) = - \sum_n \frac{\varphi_n(\xi) \varphi_n(x)}{\lambda_n \|\varphi_n\|^2}.$$

Hyperbolic Equations

$$(*) \quad u_{tt} - u_{xx} = 0$$

The characteristics are $x \pm t = \text{const.}$ Change of variables:

$$\xi = x+t, \quad \eta = x-t$$

leads to (*) reducing to

$$u_{\xi\eta} = 0.$$

The general solution is then

$$u(\xi, \eta) = F(\xi) + G(\eta)$$

$$\Rightarrow u(x, t) = F(x+t) + G(x-t).$$

If $F \equiv 0$, then u is constant along lines $x-t = \text{const.}$, and so can be described as a wave propagating in the positive x -direction, with speed $\frac{dx}{dt} = 1$. If $G \equiv 0$, then we have a wave propagating in the negative x -direction with speed $\frac{dx}{dt} = -1$.

Consider the Cauchy Problem

$$\begin{cases} u_{tt} - u_{xx} = 0 \\ u(x, 0) = g(x) \\ u_t(x, 0) = h(x) \end{cases}$$

Well

$$u(x, t) = F(x+t) + G(x-t) \quad \text{---} \quad (**)$$

together with the above ICs yields

$$F(x) + G(x) = g(x), \quad \text{--- (1)}$$

$$F'(x) - G'(x) = h(x), \quad \text{--- (2)}$$

Integrating (2) wrt x yields

$$F(x) - G(x) = \int_0^x h(s) ds + C \quad \text{--- (3)}$$

Now we solve for F and G using (1) and (3). We obtain

$$F(x) = \frac{1}{2} g(x) + \frac{1}{2} \int_0^x h(s) ds + C^*$$

$$G(x) = \frac{1}{2} g(x) - \frac{1}{2} \int_0^x h(s) ds - C^*$$

Since we have (**), we combine these to get

don't use \rightarrow (†)
$$u(x,t) = \frac{1}{2} (g(x+t) + g(x-t)) + \frac{1}{2} \int_{x-t}^{x+t} h(s) ds,$$

which is known as d'Alembert's ~~solv~~ formula.

Theorem: If $g \in C^2$, $h \in C^1$, then

(*)
$$u(x,t) = \frac{1}{2} (g(x+ct) + g(x-ct)) + \frac{1}{2c} \int_{x-ct}^{x+ct} h(s) ds$$

defines a C^2 solution of

(**)
$$\begin{cases} u_{tt} - c^2 u_{xx} = 0, \\ u(x,0) = g(x), \quad u_t(x,0) = h(x). \end{cases}$$

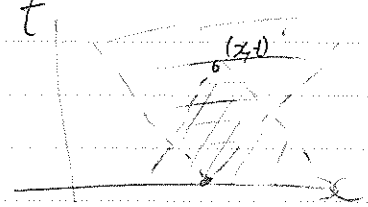
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Note: (1) (*) \Rightarrow a solution to (**) is unique (SKETCH)

(2) Small perturbations in Cauchy data g, h will affect the solution by "small" amounts (ie cont. dependence on ICs)

Note (cont.): (3) At any (x, t) , u is determined by values of g and h in the interval $[x-ct, x+ct]$, known as the domain of dependence.

Conversely, any pt ξ on the x -axis lies only in the domain of dependence of pts (x, t) in an inverted wedge shape known as the range of influence.



Physically, these ideas express the "finite propagation speed" of disturbances.

An initial disturbance near $x = \xi$ ($t=0$) will not be felt at x^* until $t^* = |x^* - \xi|/c$. (c is gone)

drop c
dependence
from now on

We might expect

$$u(x, t) = F(x+t) + G(x-t)$$

to represent a weak solution of the Cauchy problem when F and G no longer are required to be C^2 .

Let $\xi = x+t$, $\eta = x-t$.

Consider ABCD. Since F is constant along vertical lines and G is

" horizontal lines,

$$F(A) = F(D), \quad F(C) = F(B)$$

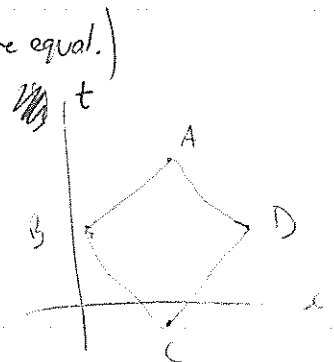
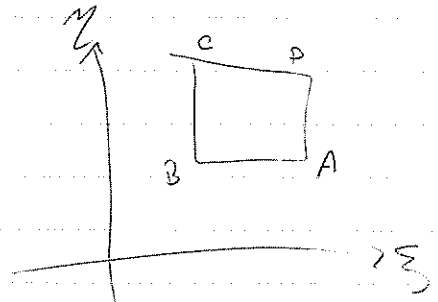
$$G(C) = G(D), \quad G(B) = G(A)$$

but $u(\xi, \eta) = F(\xi) + G(\eta)$, so

$$u(A) + u(C) = u(B) + u(D).$$

(ie sums of the value of u at opposite corners are equal.)

This is known as the parallelogram rule.

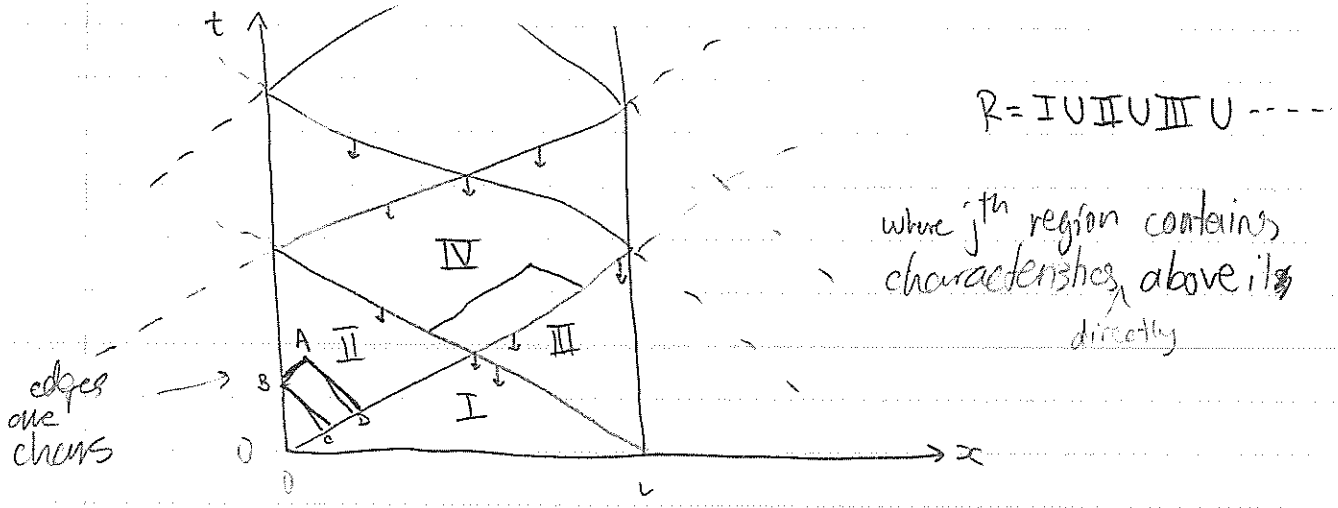


~~$u_x = 0$~~
 ~~$u_{xx} = 0$~~

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see pg 1-8 of chap 3

$$\begin{cases} u_{tt} - u_{xx} = 0 & 0 < x < L, t > 0 \\ u(x,0) = g(x), u_t(x,0) = h(x), & 0 < x < L \\ u(0,t) = \alpha(t), u(L,t) = \beta(t), & t > 0 \end{cases}$$



In I: Solution is given by d'Alembert formula

$$u(x,t) = \frac{1}{2} (g(x+t) + g(x-t)) + \frac{1}{2} \int_{x-t}^{x+t} h(s) ds$$

In II: $u(A) = \underbrace{-u(C)}_{\text{known from I}} + \underbrace{u(B)}_{\text{known from I}} + \underbrace{u(D)}_{\text{known from BC, } \alpha(t)}$

Similarly we build up u in all regions based on the ones below.

As $A \rightarrow D, B, C \rightarrow 0$ and so we get

$$u(A) = -g(0) + \alpha(0) + u_1(A)$$

To have continuity in $I \cup II$, we need $u(0) = g(0)$

Similarly we require $u'(0) = h(0)$ in order for $u \in C^1$

Inhomogeneous Wave Equation

$$(*) \begin{cases} U_{tt} - c^2 U_{xx} = F(x,t) \\ U(x,0) = 0 = U_t(x,0) \end{cases}$$

Duhamel's principle reduces this problem to the following:

$$(**) \begin{cases} V_{tt} - c^2 V_{xx} = 0 \\ V(x,0,s) = 0, \quad x \in \mathbb{R}, s \geq 0 \\ V_t(x,0,s) = F(x,s), \quad x \in \mathbb{R}, s \geq 0 \end{cases}$$

which has to be solved for each parameter value s

Duhamel's principle: If $v(x,t,s)$ is C^2 in x,t and C^0 in s , and is a solution of (**), then

$$(†) \quad u(x,t) = \int_0^t v(x,t-s,s) ds$$

solves (*).

Proof: Define u by (†). Then

$$u_t(x,t) = v(x,0,t) + \int_0^t v_t(x,t-s,s) ds = \int_0^t v_t(x,t-s,s) ds,$$

$$u_{tt}(x,t) = v_t(x,0,t) + \int_0^t v_{tt}(x,t-s,s) ds = F(x,t) + \int_0^t v_{tt}(x,t-s,s) ds,$$

$$u_{xx}(x,t) = \int_0^t v_{xx}(x,t-s,s) ds.$$

Therefore

$$u_{tt} - c^2 u_{xx} = F(x,t) + \int_0^t \underbrace{(v_{tt}(x,t-s,s) - c^2 v_{xx}(x,t-s,s))}_{=0 \text{ by } (**)} ds = F(x,t).$$

Clearly

$$u(x,0) = \int_0^0 \dots = 0, \quad u_t(x,0) = \int_0^0 \dots = 0$$

and thus u is a solution to (*).

However, we would still need to solve (**). In the 1-D case, we can use D'Alembert's formula to solve (**):

$$v(x,t,s) = \frac{1}{2c} \int_{x-ct}^{x+ct} F(\xi,s) d\xi \quad \text{provided } F \text{ is } C^1 \text{ in } x \text{ and } C^0 \text{ in } t.$$

The solution to the original problem (*) is then

$$u(x,t) = \frac{1}{2c} \int_0^{x+c(t-s)} \int_0^{x-c(t-s)} F(s,s) d\xi ds$$

is a C^2 solution of (*). It's now straightforward to solve

$$\begin{cases} u_{tt} - c^2 u_{xx} = F(x,t) \\ u(x,0) = g(x) \\ u_t(x,0) = h(x) \end{cases}$$

by considering

$$\begin{cases} u_{tt} - c^2 u_{xx} = 0 \\ u(x,0) = g(x) \\ u_t(x,0) = h(x) \end{cases} \quad \text{and} \quad \begin{cases} u_{tt} - c^2 u_{xx} = F(x,t) \\ u(x,0) = 0 \\ u_t(x,0) = 0 \end{cases}$$

and then using linear superposition.

Wave Equation in more than 1-D

Consider the pure initial value problem:

The spherical mean or the average over a sphere of radius r and centre \underline{x} (for $u(\underline{x})$ defined on \mathbb{R}^n) is:

$$(*) \quad I_u(\underline{x}, r) = \frac{1}{\omega_n \int_{|\xi|=1} dS_\xi} \int_{|\xi|=1} u(\underline{x} + r\xi) dS_\xi$$

ω_n
= surface area of unit sphere

Since u is continuous in \underline{x} , $I_u(\underline{x}, r)$ is continuous in \underline{x} . Letting $r \rightarrow 0^+$, we have $I_u(\underline{x}, 0) = u(\underline{x})$.

If $u \in C^k(\mathbb{R}^n)$ then $I_u \in C^k(\mathbb{R}^n \times [0, \infty))$. Using the chain rule on (*),

$$(**) \quad \frac{\partial}{\partial r} I_u(\underline{x}, r) = \frac{1}{\omega_n \int_{|\xi|=1} dS_\xi} \int_{|\xi|=1} u_{x_i}(\underline{x} + r\xi) \cdot \xi_i dS_\xi$$

Let $\Omega = \{\xi \in \mathbb{R}^n; |\xi| < 1\}$. Then $\partial\Omega = S^{n-1}$. The exterior unit normal is $\underline{n} = \underline{\xi}$ ($|\xi| = 1$).

The RHS of (**) can be rewritten using the divergence theorem. Recall:

$$\int_{\Omega} \nabla \cdot \underline{v}(\underline{\xi}) d\underline{\xi} = \int_{\partial\Omega} \underline{v} \cdot \underline{n} dS_{\underline{\xi}}$$

Take $\underline{v}(\underline{\xi}) = r^{-1} \nabla_{\underline{\xi}} u(\underline{x} + r\underline{\xi}) = \nabla_{\underline{x}} u(\underline{x} + r\underline{\xi})$. Compute